

Curie-Weiss theory of ferromagnetism

A ferromagnet can be seen as a crystal lattice where each site is occupied by a magnetic dipole, and magnetic dipoles want to be aligned with each other (actually real ferromagnetism is due to electrostatic interactions in a quantum mechanics formalism... but this is another story). → Heisenberg in the '20s

The energy (Hamiltonian) of the system is

$$H(\{S_i\}) = -J \sum_{\langle ij \rangle} \vec{S}_i \cdot \vec{S}_j - \vec{h} \sum_i \vec{S}_i$$

where \vec{S}_i is the magnetic dipole in i , the sum runs over nearest-neighbor pairs (dipole-dipole interactions decay quickly). The interaction J is assumed to be constant over the lattice and \vec{h} is an external field trying to align the dipoles.

Computing the magnetization in a statistical mechanics framework means computing the average of

$$\sum_i \vec{S}_i$$

$$\vec{m} = \frac{1}{N} \langle \sum_i \vec{S}_i \rangle = \frac{1}{N} \sum_i \langle \vec{S}_i \rangle$$

N is the number of dipoles

Assuming the system is homogeneous: $\vec{m} = \langle \vec{S}_i \rangle \quad \forall i$

The average is the thermodynamic average:

$$\langle \vec{S}_i \rangle = \sum_{\{\vec{S}_i\}} \vec{S}_i \frac{e^{-\beta H(\{\vec{S}_i\})}}{Z} \quad \beta = \frac{1}{k_B T}$$

where the partition function is

$$Z = \sum_{\{\vec{S}_i\}} e^{-\beta H(\{\vec{S}_i\})}$$

and the sum runs over $\{\vec{S}_i\}$, which is the set of all possible configurations (directions) of all the dipoles.

We thus have

$$\langle \vec{S}_i \rangle = \sum_{\{\vec{S}_i\}} \vec{S}_i \frac{e^{\beta J \sum_{\langle ij \rangle} \vec{S}_i \cdot \vec{S}_j + \beta h \sum_i \vec{S}_i}}{Z}$$

Unfortunately, this expression cannot be computed exactly.

The Curie-Weiss theory consists in a clever approximation (Weiss' molecular field):

$$\vec{S}_i \cdot \vec{S}_j = \vec{S}_i \cdot \langle \vec{S}_j \rangle = \vec{m} \cdot \vec{S}_i$$

Essentially each dipole "sees" the average value of the others, not their instantaneous value.

The expression then becomes:

$$\langle \vec{S}_i \rangle = \vec{m} = \sum_{\{\vec{S}_i\}} \vec{S}_i \frac{e^{\sum_i \beta \left(\frac{z}{2} \vec{m} + \vec{h} \right) \cdot \vec{S}_i}}{z}$$

z is the coordination number of the lattice, that is, the number of nearest neighbors.

of course, also z will receive the same treatment

This is a self-consistent equation: \vec{m} (l.h.s.) depends on \vec{m} (r.h.s.)

We can further simplify our lives!

The dipole-dipole interaction term is invariant for a global rotation (scalar products: depend only on relative orientation). If they align, any direction is as good as any other. But the external field breaks the symmetry: we can expect then that the global alignment (if any) will be in the direction of \vec{h} : $\vec{m} \parallel \vec{h}$

We also assume for simplicity that dipoles have unitary length,

$|\vec{S}_i| = 1 \quad \forall i$. Last but not least, we look at the component of \vec{S}_i in the direction of \vec{h} :

$$\vec{S}_i \cdot \hat{h} = \cos \theta_i$$

At last we have

$$m = \langle \cos \theta_i \rangle = \sum_{\{\vec{S}_i\}} \cos \theta_i \frac{\prod_i e^{\beta \left(\frac{z}{2} m + h \right) \cos \theta_i}}{z}$$

But z is

$$z = \sum_{\{\vec{S}_i\}} \prod_i e^{\beta \left(\frac{z}{2} m + h \right) \cos \theta_i}$$

We can now remember that actually \vec{S}_i are continuous variables (point in any direction of space) :

$$\sum_{\{\vec{S}_i\}} \longrightarrow \int_0^{2\pi} d\varphi_1 \int_0^\pi d\theta_1 \sin\theta_1 \dots \int_0^{2\pi} d\varphi_N \int_0^\pi d\theta_N \sin\theta_N$$

Thus we have (we use $i=1$, but irrelevant for generality)

$$m = \langle \cos\theta \rangle = \frac{\int_0^{2\pi} d\varphi_1 \int_0^\pi d\theta_1 \sin\theta_1 \dots \int_0^{2\pi} d\varphi_N \int_0^\pi d\theta_N \sin\theta_N \cos\theta_1 \prod_{i=1}^N e^{\beta(\frac{J}{2}m+h)\cos\theta_i}}{\int_0^{2\pi} d\varphi_1 \int_0^\pi d\theta_1 \sin\theta_1 \dots \int_0^{2\pi} d\varphi_N \int_0^\pi d\theta_N \sin\theta_N \prod_{i=1}^N e^{\beta(\frac{J}{2}m+h)\cos\theta_i}}$$

This can be factored as

$$m = \langle \cos\theta \rangle = \left[\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta e^{\beta(\frac{J}{2}m+h)\cos\theta} \right]^{N-1} \int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta e^{\beta(\frac{J}{2}m+h)\cos\theta} / Z$$

and

$$Z = \left[\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta e^{\beta(\frac{J}{2}m+h)\cos\theta} \right]^N$$

Putting these results together we have

$$m = \frac{\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta \cos\theta e^{\beta(\frac{J}{2}m+h)\cos\theta}}{\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta e^{\beta(\frac{J}{2}m+h)\cos\theta}} = \frac{\int_0^\pi d\theta \sin\theta \cos\theta e^{\beta(\frac{J}{2}m+h)\cos\theta}}{\int_0^\pi d\theta \sin\theta e^{\beta(\frac{J}{2}m+h)\cos\theta}}$$

If we call z_1 , for one site,

$$z_1 = \int_0^\pi d\theta \sin\theta e^{\beta(j\frac{z}{2}m+h)\cos\theta}$$

we can write

$$m = \frac{1}{\beta z} \frac{\partial}{\partial h} z_1 = \frac{1}{\beta} \frac{\partial}{\partial h} \ln z_1 = -\frac{\partial}{\partial h} (-k_B T \ln z_1) = -\frac{\partial F_1}{\partial h}$$

We can now compute z_1 :

$$\begin{aligned} z_1 &= \int_0^\pi d\theta \sin\theta e^{\beta(j\frac{z}{2}m+h)\cos\theta} \\ &= \frac{-1}{\beta(j\frac{z}{2}m+h)} \int_0^\pi d\theta \frac{d}{d\theta} e^{\beta(j\frac{z}{2}m+h)\cos\theta} \\ &= \frac{-1}{\beta(j\frac{z}{2}m+h)} \left[e^{\beta(j\frac{z}{2}m+h)\cos\theta} \right]_0^\pi \\ &= \frac{2}{\beta(j\frac{z}{2}m+h)} \sinh\left(\beta(j\frac{z}{2}m+h)\right) \end{aligned}$$

At last

$$\begin{aligned} m &= \frac{1}{\beta z} \frac{\partial z_1}{\partial h} = \frac{1}{\beta} \frac{\beta(j\frac{z}{2}m+h)}{2} \sinh^{-1}\left(\beta(j\frac{z}{2}m+h)\right) \cdot \\ &\quad \cdot \left[\frac{2}{\beta(j\frac{z}{2}m+h)} \cdot \sinh\left(\beta(j\frac{z}{2}m+h)\right) + \right. \\ &\quad \left. + \frac{2}{\beta(j\frac{z}{2}m+h)} \cdot \beta \cosh\left(\beta(j\frac{z}{2}m+h)\right) \right] = \\ &= \coth\left(\beta(j\frac{z}{2}m+h)\right) - \frac{1}{\beta(j\frac{z}{2}m+h)} = \mathcal{L}\left(\beta(j\frac{z}{2}m+h)\right) \\ &\quad \uparrow \text{Langevin function} \end{aligned}$$

We have at last the self-consistent equation we were looking for :

$$m = d \left(\beta \left(\frac{3}{2} m + h \right) \right)$$

NOTE: What about the components of \vec{S}_i perpendicular to \vec{h} ? They are $\sin\theta \sin\varphi$ and $\sin\theta \cos\varphi$. Since the Boltzmann weight does not depend on φ , their average is 0 because

$$\int_0^{2\pi} d\varphi \sin\varphi = \int_0^{2\pi} d\varphi \cos\varphi = 0$$

Let's study the Langevin function $d(x)$:

$$d(x) = \coth(x) - \frac{1}{x} = \frac{\cosh(x)}{\sinh(x)} - \frac{1}{x}$$

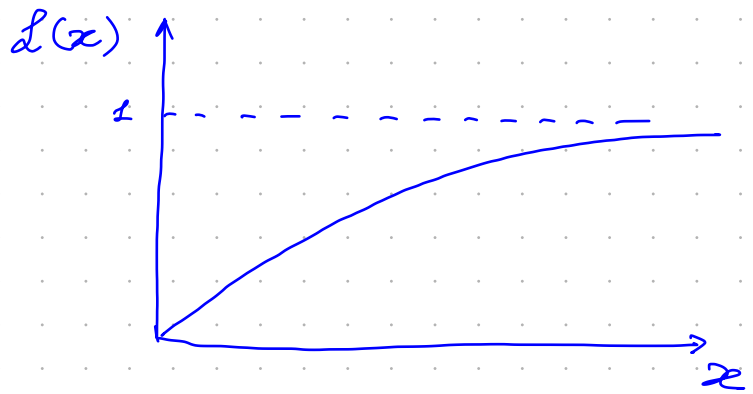
$x \rightarrow 0$:

$$\begin{aligned} d(x) &\approx \frac{1 + \frac{1}{2}x^2}{x + \frac{1}{6}x^3} - \frac{1}{x} = \frac{1 + \frac{1}{2}x^2}{x \left(1 + \frac{1}{6}x^2\right)} - \frac{1}{x} \\ &= \frac{1}{x} \left(1 + \frac{1}{2}x^2\right) \left(1 - \frac{1}{6}x^2\right) - \frac{1}{x} = \\ &= \frac{1}{x} \left(1 + \frac{1}{3}x^2\right) - \frac{1}{x} = \frac{1}{3}x \end{aligned}$$

$x \rightarrow \infty$:

$$\begin{aligned} d(x) &\approx \frac{e^x + e^{-x}}{e^x - e^{-x}} - \frac{1}{x} = \frac{1 + e^{-2x}}{1 - e^{-2x}} - 1 = \\ &= (1 + e^{-2x})(1 + e^{-2x}) - 1 = 1 - \frac{1}{x} \end{aligned}$$

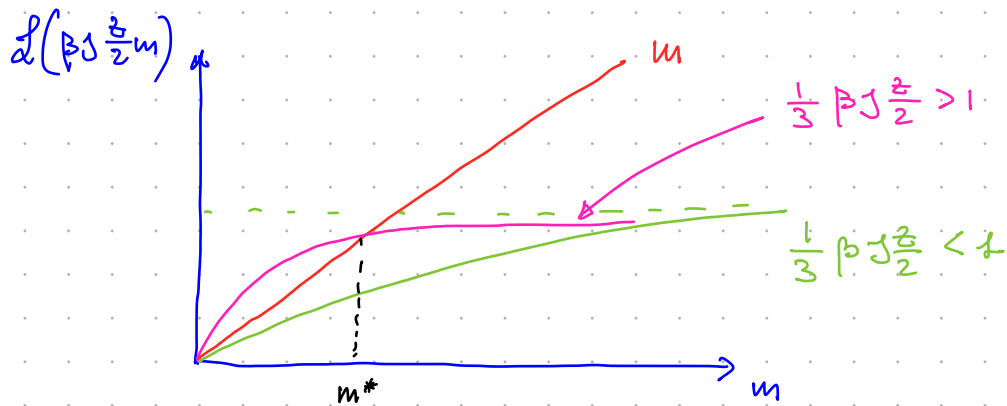
Thus



Back to the self-consistent equation:

$$m = d\left(\beta\left(\frac{Jz}{2}m + h\right)\right)$$

Let's start from $h=0$



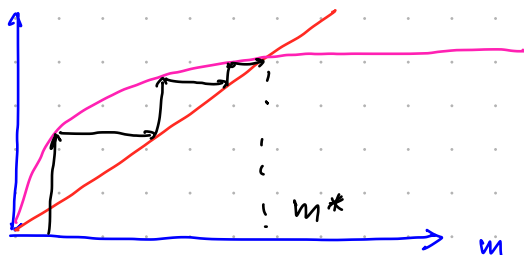
Thus, if $\frac{1}{3} \beta J \frac{z}{2} < 1$, that is $T > \frac{Jz}{6k_B}$, $m=0$ is the only solution

If $\frac{1}{3} \beta J \frac{z}{2} > 1$, then there are two solutions:

$$m=0 \quad m=m^*$$

Mathematically, $m=m^*$ is the stable solution:

iterative
solution
 m^* is stable



We will see that this corresponds to thermodynamic stability.

So we have $m(T) = \begin{cases} 0 & T > T_c = \frac{Jz}{6k_B} \\ \neq 0 & T < T_c \end{cases}$

Let's see what happens in proximity of T_c , when $m \approx 0$, recalling that

$$\begin{aligned} \mathcal{L}(x) &= \frac{\cosh(x)}{\sinh(x)} - \frac{1}{x} \approx \frac{1 + \frac{1}{2}x^2 + \frac{1}{4!}x^4}{x + \frac{1}{3!}x^3 + \frac{1}{5!}x^5} - \frac{1}{x} = \\ &= \frac{1}{x} \left(1 + \frac{1}{2}x^2 + \frac{1}{4!}x^4 \right) \left(1 - \frac{1}{3!}x^2 + \frac{1}{5!}x^4 + \left(\frac{1}{3!}\right)^2 x^4 \right) - \frac{1}{x} = \\ &= \left(\frac{1}{2} - \frac{1}{3!} \right) x + \left(\frac{1}{4!} - \frac{1}{5!} + \left(\frac{1}{3!}\right)^2 \right) x^3 = \\ &= \frac{1}{3} x - \frac{1}{45} x^3 \end{aligned}$$

Then

$$m \approx \frac{1}{3} \beta J \frac{z}{2} m - \frac{1}{45} \left(\beta J \frac{z}{2} \right)^3 m^3$$

Since we are looking for the $m \neq 0$ solution we divide by m

$$-\frac{1}{45} z^3 \left(\beta J \frac{z}{2} \frac{1}{3} \right)^3 m^2 = 1 - \frac{Jz}{6k_B T}$$

recall that $T_c = \frac{Jz}{6k_B}$ then

$$\frac{z^3}{5^3} \left(\frac{T_c}{T} \right)^3 m^2 = \frac{T_c}{T} - 1$$

Then

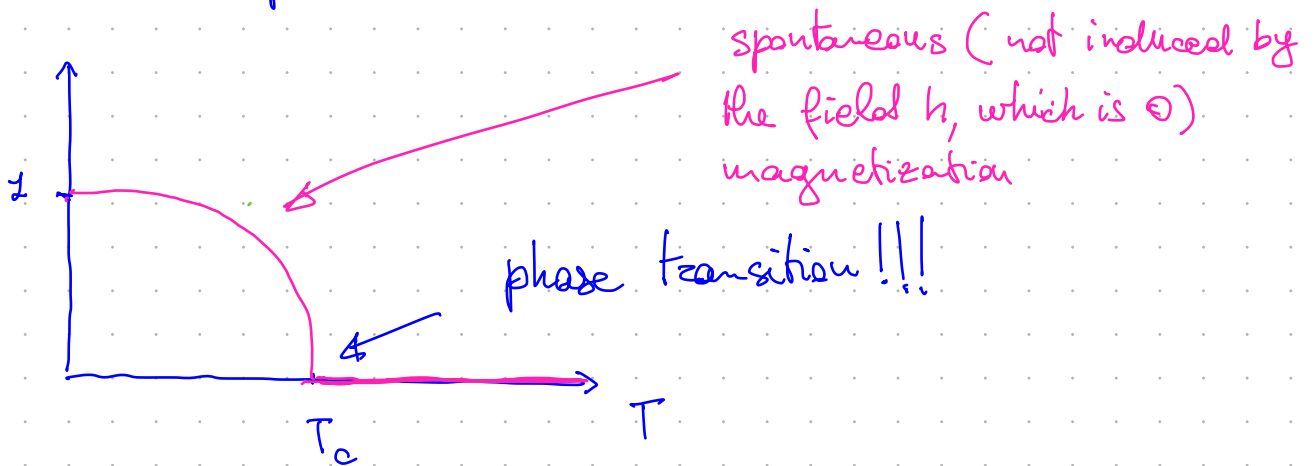
$$m^2 = \frac{5}{3} \left(\frac{T}{T_c} \right)^3 \frac{T_c - T}{T}$$

Let's choose $m > 0$ (recall, $h=0$, no preferred direction)
and $T \approx T_c$

$$m \approx \sqrt{\frac{5}{3}} \left(\frac{T_c - T}{T_c} \right)^{1/2} = \sqrt{\frac{5}{3}} t^{1/2} \quad t = \frac{T_c - T}{T_c}$$

↑ ! non analytic!

We can now plot $m(T)$

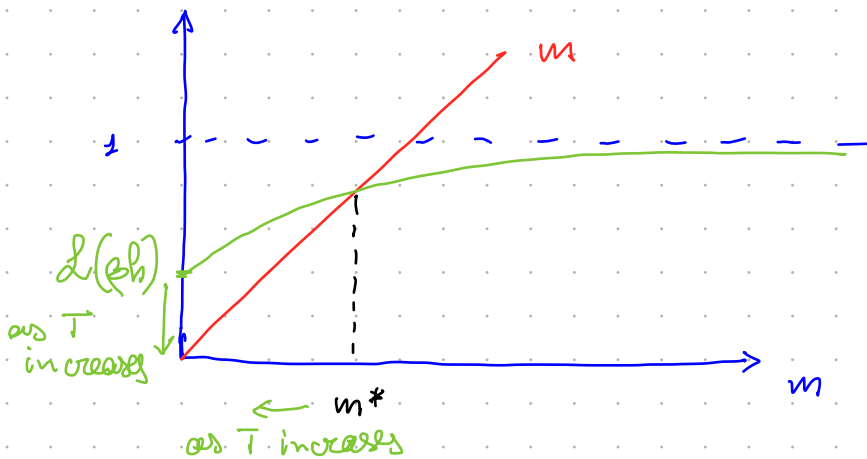


The magnetization is the first example of an

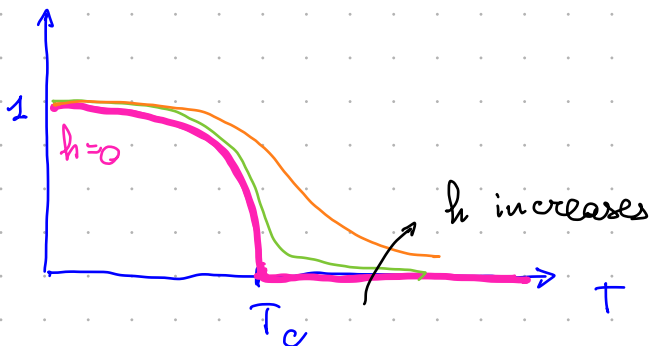
order parameter, namely a quantity with a sharp change of behavior across the phase transition and which reports about a change of order in the system

Let's examine the $h \neq 0$ case

$$m = \mathcal{L}\left(\beta\left(\frac{\mathcal{J}^2}{2}m + h\right)\right)$$



as a consequence



Remarkably, the non-analyticity is lost

Let's see what happens when $h \rightarrow 0$ and $T = T_c = \frac{\mathcal{J}^2}{6k_B}$.

We Taylor expand the self-consistent equation for $T = T_c$ and m small

$$m = \mathcal{L}\left(\beta\left(\frac{\mathcal{J}^2}{2}m + h\right)\right) = \mathcal{L}\left(\frac{\mathcal{J}^2/2}{\mathcal{J}^2/6}m + \frac{h}{k_B T_c}\right) = \mathcal{L}\left(3m + \frac{h}{k_B T_c}\right) =$$

$$\Leftrightarrow \frac{1}{3}\left(3m + \frac{h}{k_B T_c}\right) - \frac{1}{45}\left(3m + \frac{h}{k_B T_c}\right)^3 =$$

$$= m + \frac{h}{3k_B T_c} - \frac{1}{5}m^3 - \frac{3}{5}m^2 \frac{h}{k_B T_c} - \frac{1}{5}m \frac{h^2}{(k_B T_c)^2} - \frac{1}{45} \frac{h^3}{(k_B T_c)^3}$$

m on both sides cancels and we are left with

$$\frac{1}{3} \frac{h}{k_B T_c} = \frac{1}{5} m^3 + \frac{3}{5} \frac{h}{k_B T_c} m^2 + \frac{1}{5} \left(\frac{h}{k_B T_c} \right)^2 m + \frac{1}{45} \left(\frac{h}{k_B T_c} \right)^3$$



from here we get $m \sim h^{1/3}$

The next terms then are

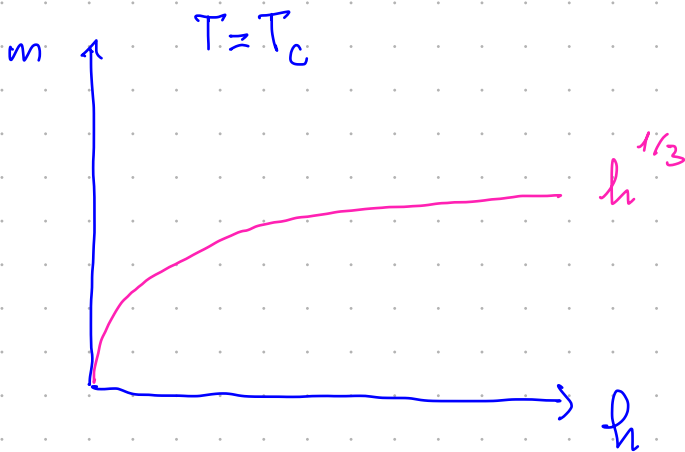
$$m^2 h \sim h^{5/3} \rightarrow 0 \quad \text{faster than } h \rightarrow \text{negligible}$$

$$m h^2 \sim h^{7/3} \rightarrow 0 \quad \text{" " " " " " " " " " " "}$$

$$h^3 \rightarrow 0 \quad \text{" " " " " " " " " " " "}$$

then the correct scaling is $m \sim h^{1/3}$ \leftarrow non-analytic behavior again!

↑
word to remember



Summary

In this treatment of a magnetic system we have encountered several leit-motifs of the whole course :

- 1) Mean-field approximation (Weiss molecular field)
- 2) Phase transition for $h \rightarrow 0$
- 3) Non analytic behavior close to, or at, T_c :

$$m \sim t^{1/2}$$

$$m \sim h^{1/3}$$

Unfortunately, the ferromagnet made by dipoles is not much useful.

We are going to revisit an apparently simpler model, the Ising model, that has played a crucial role in the development of statistical mechanics (and beyond) in the past 70 years and which continues to play, in itself and in its multiple variations.